

Technical Note

Structural Classification of Marshes with Polarimetric SAR Highlighting the Temporal Mapping of Marshes Exposed to Oil

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Abstract: Empirical relationships between field-derived Leaf Area Index (LAI) and Leaf Angle Distribution (LAD) and polarimetric synthetic aperture radar (PolSAR) based biophysical indicators were created and applied to map S. alterniflora marsh canopy structure. PolSAR and field data were collected near concurrently in the summers of 2010, 2011, and 2012 in coastal marshes, and PolSAR data alone were acquired in 2009. Regression analyses showed that LAI correspondence with the PolSAR biophysical indicator variables equaled or exceeded those of vegetation water content (VWC) correspondences. In the final six regressor model, the ratio HV/VV explained 49% of the total 77% explained LAI variance, and the HH-VV coherence and phase information accounted for the remainder. HV/HH dominated the two regressor LAD relationship, and spatial heterogeneity and backscatter mechanism followed by coherence information dominated the final three regressor model that explained 74% of the LAD variance. Regression results applied to 2009 through 2012 PolSAR images showed substantial changes in marsh LAI and LAD. Although the direct cause was not substantiated, following a release of freshwater in response to the 2010 Deepwater Horizon oil spill, the fairly uniform interior marsh structure of 2009 was more vertical and dense shortly after the oil spill cessation. After 2010, marsh structure generally progressed back toward the 2009 uniformity; however, the trend was more disjointed in oil impact marshes.

Keywords: polarimetric radar; marsh structure mapping; LAI; LAD; UAVSAR; Deepwater Horizon oil spill

1. Introduction

1.1. Optical Landcover Mapping and Canopy Structure

Marshes occupy a unique interface between water bodies and upland landscapes. They are critical and essential for exchange of land-to-water fluxes, for providing habitat, and, in coastal settings, protection of people and facilities. In the coastal interface, they experience high frequency shifts in inundation modulated by terrestrial runoff and coastal ocean tides and storms. These dynamic modulations create a spatially complex landscape exhibiting various wetland communities and canopy structure forms, even within monotypic marshes in the same region. In addition, the details of wetland management can have substantial impacts on the biophysical and compositional structure of the marshes and the animal communities dependent on these habitats. The biophysical and structural characteristics of these coastal marshes must be monitored and documented to track their health and function.

Remote sensing can provide this information by linking the optical canopy reflectance to wetland status on multiple spatial and temporal scales. However, multiple canopy contributors such as plant cover percent and background variability [1–4] complicate the linking the plant leaf condition to canopy reflectance. Even accounting for background influences, the canopy reflectance as represented in the remote sensing signal reflects the intertwined contributions of the leaf optical properties and plant canopy structure, *i.e.*, density and orientation [5–12]. Structure information can be purposely incorporated into the classification by fusing radar backscatter and optical image data [13–15]. In other cases where the target canopies exhibit largely "full and uniform coverage" or the leaf and structure are considered a combined land class unit, the decoupling of the leaf optical and plant-canopy structure contributions to the canopy reflectance can be of little consequence. However, when the objective is mapping the canopy structure or capturing subtle changes in plant leaf pigments that accompany changes in canopy condition, the determination of canopy structure or its contribution, including background, to the canopy reflectance can be critical to detecting desired changes. The incorporation of canopy structure into calibration advances remote sensing mapping of subtle changes as well as bulk canopy changes.

1.2. Standardization of Canopy Architecture

Common methods used to transform remote sensing data to estimates of biomass are based on vegetation indexes (VI) adapted from the concept of Tucker [16]. Successful application of VI to map biomass, however, has necessitated widespread modifications of the simple VI index that include changes in form and variable input (e.g., [17]) or optimization (e.g., [18]). These modifications enhance performance for specific landscapes but lead to a plethora of vegetation indexes, particularly in complex canopies [19–21]. Relationships that link radar backscatter to biomass can also be constrained in specificity of the landscape composition (e.g., [22]). This abundance of vegetation and site specific VI is a limitation of the VI approach, reducing its general applicability.

Even though broadly useful, VI mapping success is to some degree dependent on the consistency of canopy structure throughout the mapped spatial extent so that the biomass composition and canopy reflectance relationship remains substantially unaltered. That consistency and VI-based biomass mapping success at some level appears to be dependent on the live biomass to total biomass composition consistency [14,17,23,24]. While many applications indicate that consistency is often realized, a more robust remote sensing estimator of the canopy structure would insure more complete and timely accounting of biomass changes in complex canopies exhibiting highly variable structures and compositions.

1.3. Marsh Canopy Structure and Vertical Profiling

The vegetative canopy can be represented in terms of its structure as the "spatial arrangement of plant's aboveground organs in plant communities" [25]. Watson [26] standardized the leaf area index (LAI) as one component of structure describing the total one-sided leaf area per ground area (m^2/m^2) . Since these early works, numerous review articles have documented limitations and advantages of direct and indirect measurement of LAI (e.g., [20,21,23,27–29]). Some of those articles have also reported measures related to the orientations of the vegetative canopy elements, dominantly leaves and stems (e.g., [27,30,31]), which in this paper are aggregately represented as the Leaf Angle Distribution (LAD). Of the studies that report vegetation structure, most describe forest and agriculture landscapes. Although advantageous for proper monitoring and development of physical dynamics, incorporation of canopy structure profile measurements into terrestrial mapping strategy is lacking, particularly in grasslands, and within those, especially marshes.

The necessity of tracking marsh structure and vertical profile is not only based on the need for a consistent measure amenable to remote sensing, but also because of the interdependence of the marsh structure and coastal zone biophysical function. Biophysical values such as LAI have proved useful in a number of environmental applications to represent biomass density. LAI and particularly the three-dimensional spatial variability of LAI in grasslands are needed to estimate key components in biochemical cycles [27,32]. These include surface water balance and productivity (and photosynthesis) [28,33–35], and ozone and CO₂ assimilation [32,35,36]. In addition, the three-dimensional canopy description is useful for improving water flow estimates, advancing optical condition and change mapping, and fire burn dynamics and emission projections. LAI is an essential factor in climate, weather, and ecological studies, and thus, a factor in global climate [28,35].

1.4. Mapping LAI and LAD with Polarimetric Radar Data

The choice of polarimetric radar data as the base for developing a remote sensing marsh structure mapping technology is founded primarily on the requirements for defining canopy structure and density (biomass, water content, LAI, LAD). Although mapping success varies, the advantage of cross polarization backscatter (HV or VH) or cross and like (HH or VV) polarization ratios in explaining density variance is well established (e.g., [13,37–44]). Less experience exists in applying full polarimetric (PolSAR) information in mapping vegetation density, especially in grassland landscapes; however, some operational mapping applications have utilized the full polarimetric information to account for canopy structural changes in grassland or marsh landscapes [22,45–48]. This research follows those latter studies by exploiting a combination of backscatter intensities, intensity ratios,

copolarization correlation and phase, backscatter spatial heterogeneity, and backscatter mechanism obtained by decomposition of the complex polarimetric data for canopy structure mapping development. Information gained from single and dual polarization radar mapping of vegetation density and orientation was also incorporated into the study to evaluate marsh change during a time interval extending from one year before the Deepwater Horizon (DWH) spill to two years after the spill.

1.5. Coastal Description and Site Locations

Located in the deltaic plains of the north-central Gulf of Mexico, the study region encompasses estuarine wetlands [49,50] (Figure 1) located in southern Louisiana. These marshes are scoured by hurricanes that push water with elevated salinity into inland marshes where channels, levees, and impoundments impede overland flow, lengthening marsh exposure to elevated salinity surge water and prolonged inundation that promote marsh alteration and deterioration [51,52]. Features such as water ponding in scattered small depressions are a constant and changing occurrence throughout these coastal marshes. Water masks created one year may over or under estimate previous or future occurrences of these features resulting at times in the over and under correction of input datasets used in landcover classifications. Because of the possible corrupting influence of extreme values in similarity-based classifications, over correction or over removal of the scattered open water ponds is preferred.



Figure 1. The coastal marsh region of Louisiana located in the north-central Gulf of Mexico. The boxes locate Barataria Bay, Golden Meadow, and Rockefeller Refuge study regions. Golden Meadow and Rockefeller Refuge *S. alterniflor*a field sites were occupied in 2010–2012 and Barataria Bay field sites in 2011 and 2012. NASA/UAVSAR PolSAR data and field data collections were coordinated. PolSAR collections in Barataria Bay occurred from 2009 to 2012.

As reported in Ramsey *et al.* [53], marsh canopy structure varies over time and from site to site, sometimes dramatically. This occurs between different marsh species and also within a single species. An added complexity and one core reason for advancing marsh structure mapping is the often abrupt changes in canopy density and orientation within the canopy vertical profile associated with lodging. Lodging is not as pervasive in *S. alterniflora* as in, for example, *S. patens* marshes; however, it does occur and can be acute [53]. *S. alterniflora* marshes also exhibit changes in form (height, leaf width,

density) dependent on provenance and growth stage. While variation in form was not a differential variable between the three physiographic regions used in this study, marsh form (not including leaf width) and biomass composition varied highly at each site and from year to year.

2. Objectives

The goal of this research is to develop an operational and robust polarimetric remote sensing estimator of marsh canopy structure. The first objective within that goal is to create an empirical relationship between PolSAR data and marsh canopy structure based on near-coincident PolSAR and field data collections. The relationship is based on field-based LAI and LAD marsh structure and PolSAR-based indicators. The second objective is to apply the empirical relationship in order to provide a direct example of using structure information to track marsh status trends. That objective was accomplished by mapping marsh structural change over a period of time that encompassed the Deepwater Horizon oil spill impact to these marshes. The Deepwater Horizon spill was initiated on 20 April 2010, and continued releasing oil into the Gulf of Mexico approximately 50 miles from the Louisiana coast until the well was capped in July 2010. The radar data set begins in 2009 with images of the Louisiana coast pre-spill, continues in 2010 when data were collected during the spill, and follows with near-anniversary collections in 2011 and 2012. Marsh oiling from the spill was extensive only in the northeastern Barataria Bay. None of the study sites are known to have received direct oiling from the spill, and only the Barataria Bay sites were in close proximity to heavily oiled marshes. In contrast, the PolSAR data for all years covered the extended wetlands, from the coast inland, both oiled and unimpacted.

3. Methods

NASA Uninhabited Aerial Vehicle SAR (UAVSAR) conducted flights over coastal Louisiana in response to the Deepwater Horizon oil spill and its possible long-term effects on exposed coastal resources [54,55]. Specific to this study, PolSAR data were collected in June to July 2010, 2011, and 2012 of the Rockefeller Refuge, Golden Meadow and Barataria Bay study areas (shown in Figure 1). In addition, UAVSAR PolSAR was collected of Barataria Bay in June 2009, prior to the Deepwater Horizon accident. Nearly concurrent with PolSAR summer collections, field data were collected at seven sites in non-impacted and impacted marshes located in the Louisiana coastal zone. In 2010, field data were collected in the Rockefeller Refuge and Golden Meadow sites only, and at all sites in 2011 and 2012.

PolSAR and field data collections are located in three dynamically diverse regions of the coastal landscape. The furthest sites to the east lie within Barataria Bay directly adjacent to the location in the Mississippi River delta that was heavily impacted by the Deepwater Horizon oil spill in 2010 [55]. Outside the oil spill impacted area and further to the west in the Golden Meadow region are located inland marsh sites that are not exposed to wave and storm energy as is marsh in Barataria Bay, although they do experience tidal water level variations. Further west in the Rockefeller Refuge and closer to the shoreline are located the remaining sites, which lie within protected impoundments that while retaining a direct connection to the coastal ocean provide protection from wave erosion. Both the Barataria Bay and Golden Meadow regions are dominated by *S. alterniflora* marsh while different estuarine marshes create a spatial patchwork of dominance throughout the Rockefeller Refuge [50]. *S. alterniflora* comprised 100% or nearly 100% of marsh at all seven sites in this study.

3.1. Field Measurements and Post-Analyses

High variability was associated with a regional dieback centered on the Golden Meadow region [14]. Whether this event was also reflected as form and composition variation measured in the Barataria Bay and Rockefeller Refuge marshes is unclear. What was observed, however, was high variability in marsh height, density, live and dead composition, and the vertical distribution of these measures from site to site and year to year. Field data collection within 30 m by 30 m *S. alterniflora* plots followed a standard sampling strategy that provides reproducible measures within these structurally variable marshes (for detailed descriptions, see Ramsey *et al.* [14,53,56]). Biomass was measured within a 1 m² area chosen to represent the typical marsh at each site, separated into live and dead portions, dried, and weighed (for method, see [14,57]). Vertical profiles of photosynthetic active radiation (PAR) attenuation, sampled at 20 cm increments from bottom to top of the canopy, were measured every 3 m along 30 m east–west and north–south transects [14,53,56].

3.1.1. Calculation of Site-specific LAI and LAD

The site averaged PAR vertical profiles were parameterized as marsh canopy LAI profiles and average leaf-stem LAD using the method of Ramsey *et al.* [56]. For use in calibrating the PolSAR data, the vertical LAI profiles were aggregated as a single total LAI per site and time.

3.1.2. Correction of Biophysical Field Measures for Water Level

At the times of the PolSAR acquisitions, above-surface water levels at the field sites were obtained from nearby hydrologic stations operated by the Coastwide Reference Monitoring System as described in the Strategic Online Natural Resources Information System [58]. Shallow (11 cm) aboveground and subcanopy flooding occurred during the 2012 Rockefeller Refuge UAVSAR overflight. Similarly, in 2009, possible shallow (7 cm) subcanopy flooding was indicated at one of the three hydrologic stations in marshes surrounding Barataria Bay [55]. At Golden Meadow, however, subcanopy surface flooding was present during all UAVSAR collections. To account for the loss of accessible biomass, the LAI profiles and measured water depth were used to adjust measured biomass and LAI remaining above the water surface at the time of the UAVSAR collections [14]. These adjusted biomass metrics offered a more accurate depiction of PolSAR-based variable and biomass relationships, improving interpretability and extendibility of regression results.

3.2. UAVSAR PolSAR Data

The day and night mapping capabilities offered with radar systems are further extended by the UAVSAR airborne platform offering rapid response in emergencies and agility in tracking time-varying features. UAVSAR's precision repeat-track capability to within 5 m ([54]) enables direct comparison between revisit data collections, and its high transmitted power results in a higher signal-to-noise ratio compared to satellite radars. The high signal-to-noise ratio, a quantity that indicates how much of the measured signal comes from surface backscatter relative to what is generated by noise in the instrument electronics, is particularly important when using HV intensities, which are lower signal level than the HH or VV returns. A previous evaluation of the UAVSAR L-band data found that noise

intensities remained below HV backscatter associated with marshes located in the near- to far-range with the possible exception of non-vegetated land covers [54,55]. The L-band 1217.5 to 1297.5 MHz (23.8 cm wavelength) frequency of the SAR system could provide more consistent subcanopy information as suggested in inundation flood mapping [52,59], and its quadrature polarized capability, recording intensities and phases of the HH, VV, and cross-polarization (HV and VH) backscatter, allow a more complete characterization of the scattering properties [60].

This study used UAVSAR's ground range projected, calibrated, and multilooked complex image data referred to as GRD (georeferenced) products [61]. These image data reflect the amplitude and phase of the electromagnetic wave measured by the PolSAR sensor representing the complex elements of the scattering matrix [55]. The cross-polarized channels, HV and VH, are combined into a single channel based on the assumption that the HV and VH backscatter is equal for natural surfaces [62]. The GRD data at 5.338 m by 6.159 m and effective looks of 3 and 12 in the azimuth and range directions were rectified to a UTM map projection at a 5 m by 5 m pixel resolution. The NASA GRD product provided a readily usable and high fidelity polarimetric data source of high spatial resolution and repeat targeting that enabled determination and direct comparison of canopy structure between the 2009, 2010, 2011, and 2012 revisit data collections.

PolSAR-Based Biophysical Indicators

PolSAR data were extracted at each site by using a 5 by 5 and a 7 by 7 pixel rectangle centered over the field collection areas. The 2009, 2010, 2011, and 2012 PolSAR data were used to calculate site mean HH (horizontal send and receive), VV (vertical send and receive), and HV intensities. These backscatter intensities were combined to form the copolarization ratios, HH/VV, HH/(VV–HH), (HH–VV)/(HH+VV), and VV/(VV+HH), HH/HV and VV/HV, the depolarization ratios, HV/HH, HV/VV, and (HH+VV)/2HV, and ratios related to volume scatter, HV/(HH+HV) and HV/(VV+HV).

The SAR Polarimetric Workstation software module imbedded within the PCI image processing software toolkit [63] provided the site average HH–VV phase difference as a measure of the polarization properties at each marsh site, the HH and VV correlation magnitude and the real and imaginary correlation coefficient components that comprise the HH and VV correlation. In addition, produced were the coefficient of variation related to the maximum and minimum power in the polarization signature, and the pedestal height of the signature plot indicating, somewhat similar to the coefficient of variation, the heterogeneity of scattering properties within the site average.

Following a number of studies (e.g., [39,44–47,55, 64]), decomposition models were applied to the complex polarimetric backscatter components of the GRD data in order to categorize the dominant backscatter into distinct mechanisms that could reveal the structure of the vegetation [65,66]. Freeman–Durden (FD) is a physical model decomposition used to transform the scatter matrix into estimates of surface, volume, and double-bounce scatter mechanism. Cloude–Pottier (CP) decomposition extracts three eigenvectors from either the covariance or coherence matrix representation of the scatter matrix. The eigenvector values and angles are used to derive secondary variables, namely entropy, anisotropy, and alpha and beta angles that combined represent different scatter mechanisms. Revised solutions to improve FD overestimation of volume scatter (negative nonphysical solutions) in certain

environments have been offered [67,68]; however, overestimation of volume scatter was not observed in the land applications.

3.3. Defining the PolSAR-Based Indicators and Marsh Structure Relationship

Development of the empirical relationship between marsh structure and PolSAR data is based on multivariate regression analyses. The use of statistical means for this development is a first step in identifying PolSAR-based variable interactions that provide marsh structure information. First, identification should advance understanding of the physical mechanism underlying these interactions, enhancing transition to operational physical models (after Titin-Schnaider [69]). Second, sound regression models fulfill an immediate need to advance marsh condition monitoring while building a body of knowledge concerning PolSAR marsh structure mapping (after Titin-Schnaider [69]).

3.3.1. Examining the PolSAR-Based Indicator Dataset

Simple relationships were examined within and between all biophysical measurements and PolSAR-based indicators in order to identify errors in data entry and variable redundancies, and reveal simple correspondences. Entry errors were corrected and redundant PolSAR variables removed before conducting multiple regression analyses.

3.3.2. Developing Statistical Predictor Equations

Stepwise regressions (SAS® Enterprise) were conducted to determine the best set of PolSAR indicator variables for explaining the Biomass, LAI and LAD variances. To decrease autocorrelation of PolSAR-based regressor variables entered into the regression analyses, PolSAR indicator variables were eliminated that exhibited direct correspondence as noted in the scatter plots. Not all autocorrelations in the PolSAR variables were removed. In order to estimate autocorrelation of the regressors, the tolerance (TOL) and variance inflation factor (VIF) were calculated within the stepwise procedure. The TOL and VIF indicate multicolinearity of the regression coefficients and a TOL < 0.1 and a corresponding VIF > 10 indicate that the importance of the regression variable cannot be interpreted based solely on the associated coefficient magnitude (e.g., [70–72]). In order to strengthen interpretation and robustness of the regression relationship and promote comparisons, the stepwise regressions were limited to those with maximum TOL ≥ 0.1 and VIF ≤ 10 .

3.3.3. Mapping Marsh Canopy LAI and LAD

Regression equations and the corresponding regression coefficients were applied to the stepwise selected PolSAR indicator images (independent regression image variables). The resultant LAI and LAD images were calculated by multiplying the coefficient and associated image data of each independent regression variable and then summing these products and the regression intercept to obtain the LAI or LAD pixel value. Calculations were carried-out with embedded image processing tools [63]. As a demonstration of LAI and LAD capabilities for monitoring marsh structural change, the study used UAVSAR PolSAR image data collected in 2009, 2010, 2011, and 2012 before and after the 2010 Deepwater Horizon oil spill.

Composite LAI and LAD classifications were obtained by applying a centroid-based clustering procedure [63]. The cluster procedure simply identified spatially covarying groups within each yearly set of LAI and LAD images and produced a set of classes representing these groupings for each year. Individual classifications by year were used in order to emphasize the unique LAI-LAD features comprising each year's marsh landscape. Comparison then involved describing similar and unique classes and their changing coverages throughout the four-year period. Changes within the extensive interior marshes outside the expected oil penetration and those exposed and potentially exposed to oil during the 2010 Deepwater Horizon oil spill were described.

4. Results

4.1. Site-Specific Biophysical Data

Marsh biomass quantity and composition and calculated LAI and LAD varied highly between sites and over time (Table 1) [56]. Live and dead dry weight compositions highly aligned with total biomass $(R^2 > 0.87, n = 17, Figure 2)$, while LAI exhibited weak correspondence with dead biomass $(R^2 = 0.29, n = 17)$ and no correspondence with total or live biomass. Although a marsh dieback was documented for the Golden Meadow region [14], and the Deepwater Horizon oil spill impacted Barataria Bay marshes [55] over this time period, no noticeable pattern of biomass and composition grouping was clearly exhibited in the field data per region or time. The *S. alterniflora* marsh dataset exhibited a broadly distributed dataset range well suited for accomplishing the study objectives [56].



Figure 2. Total Biomass Dry Weight = $1.67 \times$ Live Biomass Dry Weight + 190.28, $R^2 = 0.91$, MSE = 26,716.40 (gr/m²) (n = 17). Dashed line represents the 95% confidence limits. For data and site labels refer to Table 1.

11304

Table 1. Field Measured and Calculated Biophysical Variables. Site labels include the site name and year collected (RF = Rockefeller Refuge, BA = Barataria Bay, GM = Golden Meadow). All entries were adjusted for the water level recorded at the time of UAVSAR collection. The Biomass Percent refers to the magnitude of that adjustment. Note: There are two biomass weights, the dry weights and water weights.

Site	Dried I	Biomass V	Weight		Stru	cture	Biomass Water Weight			
	Total	Live	Dead	Biomass	LAI	LAD	Total	Live	Dead	
	gr/m2	gr/m2	gr/m2	Percent			gr/m2	gr/m2	gr/m2	
RF3-10	1417.1	795	622.1	100%	2.75	0.88	3238	1792.8	1445.1	
RF3-11	392.3	173	219.3	100%	2.6	0.69	346.6	234.4	112.3	
RF4-11	543.4	179.5	364	100%	2.41	0.72	485.8	284	201.8	
RF3-12	1113.6	600.2	513.4	89%	2.13	0.67	1149.2	725.6	423.6	
RF4-12	623.9	328.8	295.1	89%	1.9	0.82	781.7	428	353.7	
BA25-11	520.3	191.6	328.7	100%	5.03	0.5				
BA27-11	839.9	334.9	505.1	100%	3.15	0.78				
BA33-11	681.4	229	452.4	100%	3.46	0.39				
BA25-12	1137.7	555.8	581.9	100%	3.92	0.31	3634.6	1297	2337.6	
BA27-12	2351.1	1095.1	1256	100%	4.34	0.58	4417.5	2045	2372.6	
BA33-12	571.9	429.8	142.1	100%	1.24	0.38	2408.2	1590.9	817.3	
GM397-10	1020.8	529.3	491.5	66%	3.26	1.04	444.8	252.7	192.1	
GM978-10	1320	670.3	649.7	88%	3.91	0.52	3755.2	2023.5	1731.7	
GM397-11	496	177.8	318.2	94%	3.07	0.59	587.3	272	315.3	
GM978-11	353.7	5.3	348.3	75%	2.38	0.67	305.2	10.7	294.5	
GM397-12	412	249.9	162.1	39%	1.6	0.4	270.6	118.2	152.3	
GM978A-12	313.1	166.8	146.3	29%	0.94	0.39	247.3	82.1	165.2	

4.2. PolSAR-Based Biophysical Indicators

Scatter plots revealed that most of the more complex intensity ratios directly covaried with simpler ratios. The redundant ratios removed from the regression analyses included HH/(VV–HH), (HH–VV)/(HH+VV), and VV/(VV+HH), HV/(HH+HV) and HV/(VV+HV). FD volume scatter was removed because it replicates the HV backscatter variance. In addition, only the linear values associated with each of the FD scatter mechanisms were used in the regression analyses. Close and similar correspondences also were noted between some additional PolSAR-based variables and these are discussed when pertinent to those variables selected in the stepwise regression. Although of interest in analyzing polarimetric mapping of these marshes, a full discussion of the covariances between the PolSAR indicators set is not directly pertinent to this analysis and is not included here. The final PolSAR dataset entered into the regression analyses is contained in Table 2.

4.3. Linking PolSAR Indicators and Site-Specific Marsh Canopy Biophysical Structure

4.3.1. Biomass and PolSAR Data Regressions

First calculated were relationships between dry biomass and biomass water quantities in Table 1 and the set of PolSAR-based variables listed in Table 2. In the dry biomass weight stepwise regressions, site

27-12 (notation is site-year) was an extreme outlier; however, there is no evidence that biomass measurements at that site were incorrect. Including all 17 sites, a four variable solution explained 53% of the live biomass variance and two variable solutions accounted for 42% and 39% of the total and dead biomass variance, respectively. Biomass water weight stepwise regressions used all 14 sites (three sites had missing values). A two variable solution explained 70% of the total biomass water weight, and 63% of the live biomass water weight (Table 3). Because water content is commonly used, and its explained variance is substantially higher, only PolSAR-biomass water regression statistics are included in Table 3.

4.3.2. LAI and LAD and PolSAR Data Regressions

All 17 sites were input into the LAI and LAD stepwise regressions (Tables 1 and 2). The HV/VV PolSAR indicator singularly explained 49% of the LAI variance (Table 3). The prediction equation with the highest explanation ($R^2 = 0.95$) of LAI variance included nine PolSAR-based indicators; however, some variables in the relationship contained TOLs and VIFs indicating high multicolinearity among the selected PolSAR indicators. The maximum TOLs and VIFs included in the prediction was reduced to acceptable levels by eliminating variables selected in the 95% solution. A reduced six variable solution accounted for 77% of the LAI variance (Table 3, Figure 3a). A three variable solution explained 74% of the LAD variance (Table 3, Figure 3b).



Figure 3. (a) LAI Observed = 1.00 ± 0.14 (p < 0.001) × LAI Predicted + $2.40\text{E-}14 \pm 0.416$ (p = 1.0) R² = 0.77, Mean Square Error = 0.30 LAI, (n = 17). (b) LAD Observed = 1.00 ± 0.15 (p < 0.001) × LAD Predicted + $2.24\text{E-}14 \pm 0.096$ (p = 1.0) R² = 0.74, Mean Square Error = 0.011 LAD, (n = 17). Dashed line represents the 95% confidence limits (SAS® Enterprise). For observed data and site labels refer to Tables 1 to 2.

 Table 2. PolSAR Biophysical Indicator Variables (Site labels as in Table 1.).

Site	Average Target Intensity		А	verage Rat	io	(VV+HH)	HH+2HV	Copolar	Pedestal	Coefficient	
	HH	HV	VV	HH/VV	HV/HH	HV/VV	/(2HV)	/(2HV) +VV		Height	of
	Intensity	Intensity	Intensity	Ratio	Ratio	Ratio	Ratio	Intensity	Intensity	Linear	Variation
RF3-10	0.0379	0.0038	0.0058	6.541	0.0995	0.6506	5.796	0.0512	0.0436	0.0051	0.0468
RF3-11	0.0188	0.0031	0.0068	2.762	0.1644	0.4541	4.142	0.0317	0.0256	0.0041	0.0791
RF4-11	0.0185	0.0018	0.0157	1.185	0.0996	0.1180	9.260	0.0379	0.0342	0.0061	0.0469
RF3-12	0.0215	0.0036	0.0104	2.061	0.1662	0.3424	4.470	0.0391	0.0319	0.0066	0.0826
RF4-12	0.0271	0.0033	0.0099	2.727	0.1233	0.3362	5.543	0.0437	0.0370	0.0061	0.0607
25-11	0.0341	0.0052	0.0079	4.341	0.1534	0.6659	4.010	0.0525	0.0420	0.0066	0.0678
27-11	0.0185	0.0025	0.0029	6.414	0.1324	0.8491	4.365	0.0264	0.0214	0.0025	0.0561
33-11	0.0223	0.0035	0.0059	3.796	0.1566	0.5943	4.035	0.0352	0.0282	0.0051	0.0753
25-12	0.0338	0.0070	0.0103	3.294	0.2078	0.6845	3.137	0.0581	0.0440	0.0090	0.1037
27-12	0.0215	0.0036	0.0058	3.715	0.1667	0.6194	3.806	0.0344	0.0272	0.0045	0.0776
33-12	0.0146	0.0032	0.0131	1.112	0.2217	0.2466	4.282	0.0341	0.0276	0.0058	0.1038
397-10	0.0159	0.0021	0.0105	1.508	0.1319	0.1990	6.304	0.0305	0.0264	0.0057	0.0650
978-10	0.0154	0.0023	0.0032	4.836	0.1496	0.7235	4.033	0.0232	0.0186	0.0027	0.0698
397-11	0.0131	0.0033	0.0140	0.936	0.2495	0.2334	4.147	0.0337	0.0272	0.0064	0.1123
978-11	0.0259	0.0034	0.0068	3.827	0.1328	0.5084	4.747	0.0396	0.0327	0.0060	0.0623
397-12	0.0060	0.0013	0.0142	0.420	0.2223	0.0935	7.599	0.0229	0.0202	0.0031	0.0462
978A-12	0.0093	0.0013	0.0164	0.569	0.1448	0.0823	9.526	0.0284	0.0257	0.0042	0.0398
Water	0.0004	0.0002	0.0008	0.488	0.5564	0.2715	2.740	0.0017	0.0012	0.0003	0.1260

Table 2. Cont.

Site	Freemar	nan-Durden Cloude-Pottier			tier		HH + VV	HH+VV Correlation				
	Double	Surface	Entropy	Anisotropy	Alpha	Beta	Phase	Magnitude Coeffic		fficient		
	Bounce	Scatter					Difference		Real	Imaginary		
RF3-10	0.0001	0.0322	0.5526	0.2009	43.51	12.77	24.96	0.2792	0.2531	0.1178		
RF3-11	0.0022	0.0141	0.7257	0.3121	40.21	16.45	-5.14	0.3737	0.3722	-0.0334		
RF4-11	0.0115	0.0171	0.7185	0.7255	41.04	9.95	-53.44	0.3535	0.2105	-0.2839		
RF3-12	0.0060	0.0152	0.7843	0.4382	42.41	11.22	-15.44	0.2771	0.2671	-0.0738		
RF4-12	0.0061	0.0209	0.7096	0.4501	41.62	9.66	-23.85	0.3075	0.2812	-0.1243		
25-11	0.0263	0.0000	0.6785	0.2466	45.99	18.16	-44.36	0.2086	0.1491	-0.1458		
27-11	0.0000	0.0149	0.5884	0.1941	44.72	18.75	-12.20	0.2187	0.2137	-0.0462		
33-11	0.0012	0.0165	0.7149	0.2601	45.89	15.79	5.58	0.1636	0.1628	0.0159		
25-12	0.0000	0.0232	0.7774	0.1649	46.60	14.18	-15.94	0.2002	0.1925	-0.0550		
27-12	0.0004	0.0161	0.6999	0.2098	42.65	18.91	6.11	0.3126	0.3108	0.0333		
33-12	0.0071	0.0108	0.8214	0.5231	41.96	19.41	-36.12	0.3047	0.2461	-0.1797		
397-10	0.0071	0.0130	0.7727	0.6266	40.22	11.77	9.75	0.2689	0.2650	0.0455		
978-10	0.0000	0.0120	0.6463	0.1272	43.89	17.14	31.07	0.3202	0.2743	0.1652		
397-11	0.0073	0.0101	0.8455	0.5470	42.09	29.49	9.57	0.2244	0.2213	0.0373		
978-11	0.0199	0.0025	0.6919	0.3491	47.66	14.50	63.17	0.1102	0.0497	0.0983		
397-12	0.0133	0.0030	0.6683	0.5664	53.68	8.66	-128.51	0.3886	-0.2419	-0.3041		
978A-12	0.0162	0.0054	0.6517	0.6491	49.94	7.35	-103.38	0.4626	-0.1071	-0.4500		
Water	0.0005	0.0001	0.8635	0.3371	48.75	22.45	-41.08	0.0899	0.0678	-0.0591		

Table 3. Regression models used to estimate the field-based biophysical variables. FDDB = Freeman–Durden Double Bounce, CPAlpha = Cloude–Pottier Alpha angle, HHVVPhDif = Phase difference, HHVVIM = Imaginary Correlation Coefficient, CoefVAR = Coefficient of Variation, MSE = Model Mean Square Error. Highlighted cells denote model parameters used to produce the LAI and LAD images.

Biophysical	Regression Model										
	PolSAR Variables	Parameters	Parital R ²	Pr > F	Tol-VIF	R ² (#Obs)	MSE				
Dead Biomass Water	Intercept	-317 ± 277		0.28		0.64 (14)	2.72E+05				
	HV	2901 ± 633	0.64	0.0006							
Dead Biomass Water	Intercept	-2767 ± 1062		0.0245		0.76 (14)	1.97E+05				
	HV/VV	5302 ± 1149	0.64	0.0006	0.22-4.55						
	VV	$151,\!201\pm 63,\!919$	0.12	0.0374	0.22-4.55						
Live Biomass Water	Intercept	1425 ± 219		< 0.0001		0.55 (14)	2.94E+05				
	FDDB	$-90,\!379 \pm 23,\!653$	0.55	0.0024							
Live Biomass Water	Intercept	709 ± 491		0.1765		0.63 (14)	2.60E+05				
	HV/VV	$13,\!191\pm822$	0.09	0.137	0.56-1.76						
	FDDB	$-59,\!189 \pm 29,\!540$	0.55	0.0704	0.56-1.76						
Total Biomass Water	Intercept	-428 ± 538		0.44		0.61 (14)	1.02E+06				
	HV/VV	5304 ± 1229	0.61	0.001							
Total Biomass Water	Intercept	921 ± 894		0.3249		0.70 (14)	8.61E+05				
	HV/VV	3521 ± 1497	0.61	0.0384	0.57-1.76						
	FDDB	$-97,\!330\pm53,\!790$	0.09	0.0978	0.57-1.76						
Total Biomass Water	Intercept	-2099 ± 2291		0.3811		0.75 (14)	7.88E+05				
	HV/VV	6503 ± 2540	0.61	0.0284	0.18-5.55						
	FDDB	-09253 ± 5157	0.09	0.103	0.56-1.77						
	VV	$182,252 \pm 128,231$	0.05	0.1857	0.22-4.57						
LAI	Intercept	1.45 ± 0.41		0.0029		0.49 (17)	0.6624				
	HV/VV	3.16 ± 0.82	0.49	0.0016							
LAI	Intercept	1.39 ± 0.40		0.0036		0.56 (17)	0.6154				
	HV/VV	5.98 ± 2.09	0.49	0.0016	0.14-6.89						
	HH/VV	-0.40 ± 0.27	0.07	0.1651	0.14-6.89						
LAI	Intercept	6.60 ± 2.59		0.029		0.77 (17)	0.4432				
	HV/VV	6.35 ± 1.86	0.49	0.0066	0.13-7.6						
	HH/VV	-0.437 ± 0.232	0.07	0.09	0.14-7.1						
	FDDB	69.21 ± 28.00	0.03	0.033	0.58-1.7						
	CPAlpha	-0.126 ± 0.063	0.05	0.072	0.53-1.9						
	HHVVPhDif	-0.0234 ± 0.011	0.04	0.059	0.10-10.2						
	HHVVIM	7.69 ± 3.23	0.09	0.038	0.10-10.1						
LAD	Intercept	2.14 ± 0.43		0.0002		0.58 (17)	1.97E-02				
	HV/HH	-2.42 ± 0.84	0.38	0.008	0.95-1.06						
	CPAlpha	-0.026 ± 0.0099	0.2	0.021	0.95-1.06						
LAD	Intercept	2.81 ± 0.43		< 0.0001		0.74 (17)	0.0131				
	CoefVAR	-6.47 ± 1.47	0.34	0.0007	0.83-1.21						
	CPAlpha	-0.039 ± 0.0089	0.33	0.0008	0.78-1.28						
	HHVVIM	0.398 ± 0.196	0.08	0.0637	0.79-1.26						

4.4. Mapping Marsh Canopy LAI and LAD

The black and white 2009 to 2012 continuous images in Figure 4 represent the density (LAI) and average orientation (LAD) of the marshes surrounding Barataria Bay. The LAI images were produced with a common continuous look-up table, providing direct comparability. Higher LAIs are brighter and



Figure 4. LAI (top 2009 to 2012) and LAD (bottom 2009 to 2012) were mapped based on regression models shown in Table 3. Brightness representing increasing LAI or LAD (Table 4) is directly comparable from year to year. The box shown on the 2010 LAI map approximately outlines the core oil impact region in Barataria Bay.

Table 4. Classes are aligned to best match similar LAI and LAD class means from year to year (Figure 5). Grey shading signifies a comparable class was not found in one year that existed in another year. The same color in each year signifies a similar LAI and often a similar LAD. The class colors assigned in the table match the class colors applied in Figure 5. CLS = Class, OBS = the observations (or pixels) comprising each class and MN = Mean.

2009				201	0		2011 2012																	
CI C	CLS OBS M LA	MN	MN	MN	MN	MN	MN	MN	MN	MN	MN	MN	CT C	ODG	MN	MN	CT C	ODG	MN	MN	CI C	ODG	MN	MN
CLS		LAD	LAI	CLS	OBS	LAD	LAI	CLS	OBS	LAD	LAI	CLS	OBS	LAD	LAI									
				1	13,280	0.4	11					_												
				2	33,362	0.4	9.2	1	65,121	0.31	8.8													
					109,761	0.43	7.9		223,559	0.42	7.2													
1	36,353	0.42	6.5	4	275,644	0.5	6.6		501,057	0.45	5.9		249,634	0.41	6.3									
2	252,305	0.44	4.8	5	787,565	0.62	5.3	4	912,760	0.52	4.8	2	950,110	0.45	5									
3	798,197	0.55	3.6	6	1,596,081	0.72	4	5	1,201,247	0.61	3.7	3	1,392,628	0.52	3.9									
4	1,558,891	0.66	2.6	7	867,038	0.67	2.6	6	797,528	0.68	2.5	4	1,066,460	0.61	2.8									
5	1,178,380	0.67	1.6																					

Included in the LAD images were values less than zero. With the exception of the negative values, the lowest LAD values generally were above 0.2. The highest numbers of these negative LADs occurred in 2010 and 2012 grouped in the most interior north and northeast marshes. Although there was possible shallow surface water in 2009 (<7 cm), surface flooding was not indicated in the hydrologic stations surrounding Barataria Bay at the time of the 2010 to 2012 collections. Inspection of the PolSAR image data suggested that the negative LADs could be associated with possible flooding or small open water-filled depressions (ponds). Assessment of the selected PolSAR indicator variables (Table 2) showed that the coefficient of variation, imaginary correlation coefficient, and the copolar phase difference exhibited substantial sensitivity to subcanopy flooding when over 60% of the canopy was submerged. Similar copolar phase difference sensitivity to flooded vegetation has been noted [44]. However, as noted in Table 1, a number of field sites were flooded at the times of PolSAR collections, particularly in Golden Meadow, and these sites did not exhibit abnormal responses in the regression model (Figure 3a,b). It seems more likely that ephemeral features such as ponded open water moved the calibration response outside its operational limits. This would prove a limitation of this polarimetric mapping. The cause of the invalid LAD estimates is being pursued, and once confirmed, the limitation will be reported and avoidance incorporated into the mapping. Neighborhood pixels should also be cautiously interpreted when they exhibit extreme LAI and LAD values. Negative outcomes were excluded from subsequent analyses by combining them into the open-water mask. Excluding the areas covered by the water mask, the LAI and LAD image pairs were used to produce the LAI-LAD 2009 to 2012 classified maps (Figure 5).

Composite Marsh Canopy LAI and LAD Changes

Composite LAI-LAD classifications were created to uncover the spatial relationship between LAI and LAD magnitudes. In order to improve interpretability of the 2009–2012 LAI-LAD classified maps, Table 4 was constructed so as to emphasize the year-to-year relationship of class means (MN) and

dominance in the marsh landscape per year. As seen in Table 4, except for Class 7 in the 2010 classification, LAI progressively increases as LAD decreases. The table also reveals the change in marsh complexity as indicated by the number of classes. The least complex marsh landscapes were exhibited in 2009 and 2012, and the most complex in 2010 and 2011. Changes depicted in Table 4 show a shift in dominance in 2009 from a low to moderate LAI (1.6 to 2.5) to a moderately high LAI around 4 in 2010 while retaining a mixed orientation canopy. Although proportionally of low abundance, three high LAI and more vertical (LAI > 7, LAD ~ 0.4, Table 4) classes appeared in 2010 as well as the loss of the lowest LAI (highest LAD) class occurring in 2009. By 2011, class dominance had shifted to a slightly decreased LAI and LAD, and while two of the highest LAI classes remained, the extreme LAI and LAD class (LAI = 11, LAD = 0.4) appearing in 2010 was absent. The class composition of 2012 retained only the lowest four of the six 2011 LAI classes, and aside from lacking the lowest LAI class, its class distribution displayed progressive similarity to that exhibited in 2009.



Figure 5. LAI-LAD classes (2009 to 2012). See Table 4 for the LAI-LAD color legend, which specifies the classes by number and color code, and their LAI and LAD means. The approximate core oil impact area is depicted in Figure 4 (LAI 2010). Most pixels fall into the moderate to moderate-high LAI classes (green through brown). Within these classes, the green classes have higher LAI than the brown (bright green = highest, dark brown = lowest), and lower LAD, although for LAD the brighter (darker) of the two green (brown) classes is not always the lowest (highest) LAD (exception in 2010). Red pixels have the highest (lowest) LAI (LAD). A detailed discussion is given in Section 4.4.1.

The produced LAI-LAD maps exhibited substantial changes from 2009 to 2012 (Figure 5). As in construction of Table 4, yearly comparability of class distributions and changes are promoted by using the same color from year to year for similar classes. The 2009 classified map displayed a low LAI and high LAD class that although spatially extensive in 2009 was not uniquely present after 2009. By 2010, there was a fairly dramatic and ubiquitous increase in LAI accompanied by a slight increase in LAD. Associated with the overall density increase, marsh exhibiting the highest LAIs (LAI = 6.5 and 4.8, Table 4) found in the northeast of the 2009 map now extended throughout the interior marsh. A minor component contained within the heart of this expansion included more vertically oriented marshes of much higher LAIs (LAI > 7, Table 4, Figure 5). These highest LAI (lowest LAD) classes were spatially associated with the out-of-bounds LADs that indicated incompatibility of the inferred LAD relationship. Although invalid LADs were eliminated from the landcover classifications, their spatial alignment with the most extreme 2010 LAI-LAD classes warrants caution in interpreting these highest values. Also in 2010, LAI increases in the core oil impacted marshes (Figure 5) followed the overall trend of the non-impacted and more interior marsh; however, within some core islands LAI increases in the interior marsh lagged those in the more nearshore marsh facing the Barataria Bay entrance.

There was a slight LAI and accompanying LAD decrease by 2011 in all marsh classes (Table 4, Figure 5). Within the overall LAI and LAD decreases, the most extreme 2010 LAI marsh class disappeared and the two remaining extreme classes of 2010 had diminished by 2011. The number of pixels containing invalid LADs also decreased from 2010 to 2011. The 2009 to 2010 spatial extension of the next highest LAI classes continued in 2011, increasingly dominating the interior marshes and occupying some nearshore marshes as well. Core island marshes tended to exhibit somewhat lower nearshore LAIs than in 2010, resulting in a more uniform marsh. Overall the 2011 classified map portrayed decreased extreme classes, a spatial expansion of moderately higher LAI and lower LAD marshes, and good preservation of marshes exhibiting somewhat lower LAIs and LADs relative to the 2010 map.

By 2012, the extreme classes first appearing in 2010 had disappeared and the expansion of moderately higher LAI classes had reversed. As a result, the lower classes expanded; however, the transforming marsh structure was associated with a more heterogenic interior marsh landscape than observed in 2010 to 2011. Within the oil impact core region, however, the 2012 marsh landscape was reminiscent of 2009. High uniformity of the core marshes, particularly island marshes, was reestablished. Overall, the 2012 marsh landscape seemed to be reverting toward the landscape of 2009.

5. Discussion

5.1. Regression Models

S. alterniflora marsh canopy structure was related to PolSAR data by deriving empirical relationships between polarimetric SAR scattering properties and site-specific canopy biomass, LAI (density), and LAD (orientation) structure indicators. The site-specific polarimetric backscatter was represented by a combination of backscatter intensities, intensity ratios, copolarization correlation and phase, backscatter spatial heterogeneity, and backscatter mechanisms obtained by decomposition of the complex polarimetric data.

5.1.1. Regression Model Accuracy, Error, and Uncertainty

Residual quantile and distribution of the residual plots indicate normality of the error in both the LAI and LAD regression models listed in Table 3. Residuals *versus* PolSAR independent variable plots are well distributed about zero also satisfying the statistical requirements for conducting regression analysis. The mean-square-error values indicate prediction accuracies of ± 0.44 for LAI and ± 0.13 for LAD with the suite of PolSAR-biophysical variables input into each regression. The observed *vs.* predicted plots confirm a one-to-one correspondence and zero bias on the prediction (Figure 3). The TOL and VIF values indicate low collinearity of the independent variables entered into the LAD regression, and although acceptable, higher collinearity of the independent variables in the LAI regression (Table 3). The higher collinearity means higher uncertainty in assessing the importance of each PolSAR variable in the LAI regression. However, the relatively low prediction errors, normal residual distributions, and nonbiased and one-to-one observed and predicted correlations combined with the stepwise partial regression R² values allowed cautious examination of the PolSAR variable composition.

5.1.2. Leaf Area Index

PolSAR indicator variables comprising the LAI regression model were a mix of intensity ratios, backscatter mechanisms obtained through decomposition, and copolar phase difference and coherence (Table 3). The series of regression models obtained through incremental increases in the stepwise tolerance criteria shows that HV/VV (or VH/VV, absent in this dataset) dominates explanation of the LAI variance, a result that is well established in the literature. Most often the correspondence is with changes in gravimetric dry biomass weight or vegetation water content (VWC) and incorporates HV intensity singularly or as HV/VV or HV/HH intensity ratios. The result also conforms to the VWC regression results (Table 3). The HV/VV ratio was the dominant or one of the two dominant PolSAR-based regressors in the dead and total biomass stepwise regression models. Although the HH/VV ratio was of secondary importance in explaining LAI variance, the ratio has shown a relationship to biomass and LAI (e.g., [73,74]).

Of the secondary variables, the FDDB and CPAlpha regressors (refer to Table 3 for definitions) captured changes in the scatter mechanism as defined in Freeman–Durden and Cloud–Pottier decompositions, respectively. The imaginary correlation coefficient (range 0.17 to –0.45) has a relatively high model partial R² value, and, as manifested in borderline TOL and VIF, a high linear correspondence with the HH and VV phase difference (range 63° to -128°) (Table 3). The high covariation reflects the complex correlation influence on the phase difference [75]. Judging by the overall low magnitude real correlation coefficient (range of 0.18 ± 0.15), backscatter at HH and VV are largely uncorrelated [76]. The high ranges of the imaginary coefficient and phase difference and the uncorrelated HH and VV backscatter indicate the diverse structural complexity of the marshes sampled. This diversity is reflected in the regressor set that, although dominated by intensity ratios indicating volume scatter, includes secondary regressors reflecting the scatter coherence and other scatter mechanisms.

5.1.3. Leaf Angle Distribution

The best two regressor solution for mapping LAD included the intensity ratio, HV/HH, and the Cloude–Pottier Alpha angle (CPAlpha) reflecting changes in the scatter mechanism (Table 3). Separate correlation analysis found the HV/HH ratio did not covary with the HV/VV ratio, the dominant LAI regressor. This finding supports uncorrelated backscatter at HH and VV, and shows the independence of the two volume scatter ratios as related to this *S. alterniflora* dataset. The three regressor model retained CPAlpha, and replaced the HV/HH ratio with the coefficient of variation (CoefVAR) and imaginary correlation coefficient (HHVVIM) (Table 3). In this dataset, HHVVIM is strongly related with the copolar phase difference. The coefficient of variation (range 0.11 to 0.040) corroborates the uncorrelated backscatter at HH and VV indicated by the real correlation coefficient and suggests the backscatter is mostly unpolarized, or that the spatial texture at each marsh site is generally homogenous.

5.2. Applying the Regression Models to Map Marsh Canopy LAI and LAD

The sets of yearly LAI and LAD continuous maps (Figures. 4 and 5) and the combined LAI-LAD classified maps exhibit a spatially extensive increase in marsh LAI from 2009 to 2010. Within that overall density increase, LAD, fairly uniform in 2009, divided into two broad groups. Lower LAD signifying more vertical oriented marsh spatially covaried with marsh of higher density (LAI), while more horizontal marshes were associated with the lower LAI ranges. Of the former classes, minor classes exhibiting the most extreme LAIs occupied the heart of the expanded regions and were more spatially aligned with invalid LAD values. While all pixels having invalid LAD's were excluded in the classification, the highest LAIs represented in these classes should also be interpreted cautiously. However, the remaining classes dominated the relatively more vertical and dense marshes extending far beyond this highest LAI class found at the center of their expansion. The extensiveness and persistence of these more vertical and dense interior marshes through 2011 indicate a pattern of new growth in 2010. Overall, LAD became more spatially uniform and LAI broadly decreased by 2011 with some selectively higher decreases along marsh shorelines impacted in the 2010 oil spill. These trends continued into 2012 with island marshes in the oil impact core portraying the sharpest LAI decline.

Aside from the somewhat disjointed trends of islands marshes within the oil spill core impact, the 2010 abrupt LAI increase in interior marshes may have been part of a regional trend. Optical and UAVSAR image data collected in 2010 to 2012 to the northwest and inland of Barataria Bay captured a dramatic dieback of marsh from 2010 to 2011 [14]. Results of the mapping found that in 2010 dieback marshes contained higher biomass quantity and live composition than surrounding non-dieback marshes. The cause of that 2011 sudden dieback was unresolved; however, in this case, there was an action in response to the oil spill that could have promoted increased coastal marsh growth in both these marshes and marshes surrounding Barataria Bay.

In order to help prevent oil from reaching coastal wetlands during the DWH spill event, freshwater releases from the Mississippi River were increased or initiated from locations ranging from just upriver of New Orleans to downriver in the delta north of Barataria Bay [77–80]. The largest of these releases began on 30 April 2010, ten days after the DWH spill began, with the specific intent of lessening oil entry into Barataria Bay. The UAVSAR data were acquired during the spill on 23 June 2010. Whether this release

or other freshwater releases between the 2009 and 2010 UAVSAR acquisitions were responsible for the increased growth, and thereby a change in marsh structure from 2009 to 2010, has implications on whether backscatter changes in the oil core interior marshes as noted by Ramsey *et al.* [55] were a direct result of oil presence. Although the high changes in marsh structure were outside the core impact area, moderate increases in LAI also occurred in core oil impact marshes. Shoreline oiling and concurrent backscatter change were confirmed, as was the presence of low concentrations of oil in core interior marshes at the time of the documented backscatter change [81]. However, the causal mechanism of the backscatter change in the core interior marshes located straight inland of the oiled shorelines was not determined. These results indicate changes of backscatter in the interior marshes of the core impact area could have resulted fully or in part from a change in marsh structure from 2009 to 2010.

The possible role of oil distributed into the interior marshes within the core region in combination with structure change is not directly determinable based on the 2009 to 2010 marsh structure maps. While oil related causes of backscatter in the interior marsh in 2010 are not excluded, changes after 2010 suggest there could have been a longer-term differential response of structure within the core region. Nearly immediate changes to marsh have been noted, especially when exposed to oil during the growing season [82]. Longer-term changes associated with oil exposure were reported by Burk [83], and recent findings point to a longer-term response of marsh associated with oil contained in the sediment [84]. A more thorough examination is required into the relationships between the dramatic 2009 to 2010 marsh structure change, elevated freshwater inputs, the 2009 to 2010 backscatter change, and the combined occurrences of oil exposure and marsh structure change. Those relationships are being further explored and will be reported as analyses are completed.

6. Conclusions

Field measurements collected at seven S. alterniflora marsh sites over a two to three year period in coordination with polarimetric synthetic aperture radar (PolSAR) data collected from the NASA UAVSAR platform were used to create empirical relationships between the marsh leaf area index (LAI) and leaf angle distribution (LAD) and PolSAR-based biophysical indicators in order to advance observation of wetland vegetation type and health status through use of radar remote sensing. This study used field data acquired at seven test sites, three in Barataria Bay, two at Golden Meadows, and two at Rockefeller Refuge, and is unique in having one acquisition (2009) a year before the Deepwater Horizon spill occurred, one during the spill (2010), and two post-spill (2011-2012), with the post-spill acquisitions timed to nearly match tidal conditions of the 2010 acquisition. The results show that the explanatory power of the polarimetric relationships with LAI equaled or exceeded relationships with typical field collected data, namely dead, live, and total vegetation water content (VWC). The HV/VV intensity ratio singularly explained 49% of the LAI variance, and in a two regressor solution, HV/HH explained 38% of LAD variance. A six regressor model was necessary to explain 77% and a three regressor model for explaining 74% of the LAI and LAD variance, respectively. Secondary regressors in the six variable LAI regression model were HH and VV coherence and phase difference and variability in backscatter mechanics. Similar secondary information was used in the three variable LAD regression model, but no intensity ratio was included. Instead, a PolSAR-based regressor was selected emphasizing the fractional polarization or the homogeneity of the site area. Results of this work offer a methodology

where remote measurements of PolSAR parameters can be used in place of field measurements to increase the spatial extent and information content of marsh classifications.

This study is unique in using data from UAVSAR, which is a fine resolution, low noise, L-band synthetic aperture radar, to obtain higher accuracy and greater sensitivity in the PolSAR parameters, which led to more accurate regression analysis for landscape mapping. Future studies could constrain the classes better if more sites were used. The study demonstrates the improved monitoring performance for appraising wetland condition and dynamics offered by polarimetric data, particularly when used to map canopy structure. Advanced performance was demonstrated in the mapping of previously unknown trends of marsh structure in and near oil impacted coastal wetlands that underwent widespread growth and subsequently a progressive decline in 2009–2012, the years encompassing the Deepwater Horizon spill. The near weather-independent and daylight-independent operational capabilities of radar-based landscape mapping enhance responsiveness to emergencies and adherence to planned collection strategies independent of weather conditions. Combined with optical mapping, these new polarimetric mapping capabilities will more fully describe, and therefore track, wetland status and trends.

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Author Contributions

Elijah Ramsey III, Amina Rangoonwala, and Cathleen Jones conceived the study. Elijah Ramsey III and Amina Rangoonwala performed the field collections and PolSAR data analysis. Elijah Ramsey III, Amina Rangoonwala, and Cathleen Jones wrote the manuscript. All authors read and approved the final manuscript.

Conflicts of Interest

The authors declare no conflict of interest.

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